# Almost Kähler Walker four-manifolds 

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#### Abstract

It is shown that any proper almost Hermitian structure on a Walker four-manifold is isotropic Kähler. Moreover, a local description of proper almost Kähler structures that are self-dual, *-Einstein or Einstein is given. This is used to supply examples of indefinite non-Kähler almost Kähler structures which are self-dual, Ricci flat and $*$-Ricci flat.


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## 1 Introduction

An almost Hermitian structure on a manifold $M$ consists of a nondegenerate 2-form $\Omega$, an almost complex structure $J$ and a metric $g$ satisfying the compatibility condition $\Omega(X, Y)=g(J X, Y)$. If the 2 -form $\Omega$ is closed (i.e., it is a symplectic form) the structure is said to be almost Kähler and $(g, J)$ is said to be Kähler if, in addition, the almost complex structure $J$ is integrable (i.e., it is defined by a complex coordinate atlas on $M)$. It is worth emphasizing that each two of the objects $(g, J, \Omega)$ determine the third one. However, whenever the starting point is a symplectic structure $\Omega$, there are many different pairs $(g, J)$ of almost Hermitian structures sharing the same Kähler form $\Omega$.

A long standing problem in almost Hermitian geometry is to relate the properties of the structure $(g, J, \Omega)$ with the curvature of $(M, g)$. For example the Goldberg conjecture [13], which claims that compact almost Kähler Einstein manifolds are necessarily Kähler, is still an open problem. (See the survey [1] for an update on the integrability of almost Kähler structures). Although the Goldberg conjecture is of global nature it is already known that some additional conditions suffice to show the integrability of the almost complex structure at the local level. For instance, Einstein almost Kähler metrics which are also *-Einstein are necessarily Kähler [22]. (The $*$-Einstein condition can be replaced by the second Gray curvature identity or the anti-self-duality condition and the integrability still follows [1]). Attention should be paid to the fact that all the above results are true in the Riemannian setting (i.e., the induced metric $g(\cdot, \cdot)=\Omega(J \cdot, \cdot)$ is positive definite). Proofs usually make use of relations involving some curvature terms (e.g. $\tau-\tau^{*}=\frac{1}{2}\|\nabla \Omega\|^{2}$ ) from where one obtains $\|\nabla \Omega\|^{2}=0$, which shows the desired integrability (see, for example [24]). Even though such identities remain valid in the indefinite setting, one may expect that the condition $\|\nabla \Omega\|^{2}=0$ defines a class of indefinite almost Hermitian structures strictly containing the Kähler ones, and this is indeed the case (see [3], [11]). Our purpose in this work is to show that the class of isotropic Kähler structures is larger than expected and it provides examples showing that the results mentioned above are not true for indefinite metrics. To do this we consider Walker metrics [25] on 4-manifolds together with the so-called proper almost complex structures [20] and obtain a local description of those metrics which are almost Kähler and self-dual, *-Einstein or Einstein. Note that an indefinite strictly almost Kähler Einstein metric on an 8-dimensional torus has been recently reported in [21].

As a notational fact, since throughout this paper we only deal with metrics of signature $(++--)$, the word indefinite will be omitted in what follows.

[^0]
## 2 Preliminaries

Throughout this paper we use the following convention for the curvature tensor $R(X, Y)=\nabla_{[X, Y]}-$ $\left[\nabla_{X}, \nabla_{Y}\right]$, where $\nabla$ denotes the Levi-Civita connection. $\rho(X, Y)=\operatorname{trace}\{U \rightsquigarrow R(X, U) Y\}$ and $\tau=$ trace $\rho$ are the Ricci tensor and the scalar curvature, respectively. As usual, $(M, g)$ is said to be Einstein if $\rho=\frac{\tau}{n} g, n=\operatorname{dim} M$, in which case the scalar curvature is necessarily constant. A special class of Einstein manifolds is that of Osserman ones, i.e., those pseudo-Riemannian manifolds whose Jacobi operators $R_{X}=R(X, \cdot) X$ have eigenvalues independent of the direction and the basepoint. (See, for example [4], [9], [10], [12] and the references therein for more information). Osserman metrics have a special significance in dimension four, since an algebraic curvature tensor on a four-dimensional vector space is Osserman if and only if it is Einstein and self-dual (or anti-self-dual) [10], [12] (see also [5]).

Associated to an almost Hermitian structure $(g, J)$ we consider the $*-$ Ricci tensor defined by $\rho^{*}(X, Y)=\operatorname{trace}\left\{U \rightsquigarrow-\frac{1}{2} J R(X, J Y) U\right\}$ and the $*$-scalar curvature $\tau^{*}=$ trace $\rho^{*}$. Note that both $\rho$ and $\rho^{*}$ coincide in the Kähler setting but $\rho^{*}$ is not symmetric in general. An $n$-dimensional almost Hermitian manifold $(M, g, J)$ is called weakly $*$-Einstein if $\rho^{*}=\frac{\tau^{*}}{n} g$ and is said to be $*$-Einstein if, in addition, $\tau^{*}$ is constant.

### 2.1 Four-dimensional Walker metrics

A Walker manifold is a triple $(M, g, \mathcal{D})$ where $M$ is an $n$-dimensional manifold, $g$ an indefinite metric and $\mathcal{D}$ an $r$-dimensional parallel null distribution. Of special interest are those manifolds admitting a field of null planes of maximum dimension $r=\frac{n}{2}$. Since the dimension of a null plane is $r \leq \frac{n}{2}$, the lowest possible case is that of $(++--)$-manifolds admitting a field of parallel null two-planes.

For our purposes it is convenient to use special coordinate systems associated to any Walker metric. Recall that, by a result of Walker [25], for every Walker metric $g$ on a 4-manifold $M$, there exist local coordinates $(x, y, z, t)$ around any point of $M$ such that the matrix of $g$ in these coordinates has the following form

$$
g_{(x, y, z, t)}=\left(\begin{array}{cccc}
0 & 0 & 1 & 0  \tag{1}\\
0 & 0 & 0 & 1 \\
1 & 0 & a & c \\
0 & 1 & c & b
\end{array}\right)
$$

for some functions $a, b$ and $c$ depending on the coordinates $(x, y, z, t)$. As a matter of notation, throughout this work we denote by $\partial_{i}$ the coordinate tangent vectors, $i=x, \ldots, t$. Also, $h_{i}$ means partial derivative $\frac{\partial h}{\partial i}, i=x, \ldots, t$, for any function $h(x, y, z, t)$.

Observe that Walker metrics appear as the underlying structure of several specific pseudo-Riemannian structures. Some of those, as in the examples below, clearly motivate the investigation of pseudoRiemannian manifolds carrying a parallel degenerate plane field. Moreover, indecomposable metrics of neutral signature which are not irreducible play a distinguished role in investigating the holonomy of indefinite metrics. Those metrics are naturally equipped with a Walker structure (see for example [2] and the references therein).

## 2-step nilpotent Lie groups with degenerate center

Let $N$ be a 2 -step nilpotent Lie group with left-invariant pseudo-Riemannian metric tensor $\langle\cdot, \cdot\rangle$ and Lie algebra $\mathfrak{n}$. In the Riemannian case, one splits $\mathfrak{n}=\mathfrak{z} \oplus \mathfrak{z}^{\perp}$ where the superscript denotes the orthogonal complement with respect to the inner product and $\mathfrak{z}$ stands for the center of $\mathfrak{n}$. In the pseudo-Riemannian case, however, $\mathfrak{z}$ may contain a degenerate subspace $\mathfrak{U}$ for which $\mathfrak{U} \subseteq \mathfrak{U}^{\perp}$. Hence the following decomposition is introduced in [6]

$$
\mathfrak{n}=\mathfrak{z} \oplus \mathfrak{b}=\mathfrak{U} \oplus \mathfrak{Z} \oplus \mathfrak{D} \oplus \mathfrak{E}
$$

in which $\mathfrak{z}=\mathfrak{U} \oplus \mathfrak{Z}$ and $\mathfrak{b}=\mathfrak{D} \oplus \mathfrak{E}$. Here $\mathfrak{U}$ and $\mathfrak{D}$ are complementary null subspaces and $\mathfrak{U}^{\perp} \cap \mathfrak{D}^{\perp}=$ $\mathfrak{Z} \oplus \mathfrak{E}$. (Indeed, $\mathfrak{Z}$ is the part of the center in $\mathfrak{U}^{\perp} \cap \mathfrak{D}^{\perp}$ and $\mathfrak{E}$ is its orthogonal complement in $\mathfrak{U}^{\perp} \cap \mathfrak{D}^{\perp}$ ). The geometry of a pseudo-Riemannian two-step nilpotent Lie group is essentially controlled by the linear mapping $j: \mathfrak{U} \oplus \mathfrak{Z} \rightarrow \operatorname{End}(\mathfrak{D} \oplus \mathfrak{E})$ defined by $\langle j(a) x, y\rangle=\langle[x, y], \mathfrak{i} a\rangle$, where $\mathfrak{i}$ is an involution
interchanging $\mathfrak{U}$ and $\mathfrak{D}$. Now, since $[\mathfrak{n}, \mathfrak{n}] \subseteq \mathfrak{z}$, it immediately follows that $\mathfrak{U}$ is a parallel degenerate subspace and thus the metric $\langle\cdot, \cdot\rangle$ is necessarily a Walker one.

On the other hand, note that four-dimensional indefinite Kähler Lie algebras $\mathfrak{g}$ naturally split into two classes depending on whether a naturally defined Lagrangian ideal $\mathfrak{h}$ satisfying $\mathfrak{h} \cap J \mathfrak{h}$ is trivial or $\mathfrak{h} \cap J \mathfrak{h}$ coincides with $\mathfrak{g}$. If the second possibility occurs, then the induced metric is a Walker one. Such Lie algebras correspond to the cases $\mathbb{R} \times \mathfrak{h}_{3}, \mathfrak{a f f}(\mathbb{C}), \mathfrak{r}_{4,-1,-1}, \delta_{4,1}$ and $\delta_{4,2}$. (See [23] for details).

## Para-Kähler and hyper-symplectic structures

A para-Kähler manifold is a symplectic manifold admitting two transversal Lagrangian foliations (see [7], [16]). Such a structure induces a decomposition of the tangent bundle TM into the Whitney sum of Lagrangian subbundles $L$ and $L^{\prime}$, that is, $T M=L \oplus L^{\prime}$. By generalizing this definition, an almost para-Hermitian manifold is defined to be an almost symplectic manifold ( $M, \Omega$ ) whose tangent bundle splits into the Whitney sum of Lagrangian subbundles. This definition implies that the (1, 1)-tensor field $J$ defined by $J=\pi_{L}-\pi_{L^{\prime}}$ is an almost paracomplex structure, that is $J^{2}=i d$ on $M$, such that $\Omega(J X, J Y)=-\Omega(X, Y)$ for all $X, Y \in \Gamma T M$, where $\pi_{L}$ and $\pi_{L}^{\prime}$ are the projections of $T M$ onto $L$ and $L^{\prime}$, respectively. The 2 -form $\Omega$ induces a nondegenerate ( 0,2 )-tensor field $g$ on $M$ defined by $g(X, Y)$ $=\Omega(X, J Y)$, where $X, Y \in \Gamma T M$. Now the relation between the almost paracomplex and the almost symplectic structures on $M$ shows that $g$ defines a pseudo-Riemannian metric of signature $(n, n)$ on $M$ and moreover, $g(J X, Y)+g(X, J Y)=0$, where $X, Y \in \Gamma T M$. The special significance of the paraKähler condition is equivalently stated in terms of the parallelizability of the paracomplex structure with respect to the Levi-Civita connection of $g$, that is $\nabla J=0$. The paracomplex structure $J$ has eigenvalues $\pm 1$ with completely degenerated corresponding eigenspaces due to the skew-symmetry of $J$. Moreover, since $J$ is parallel in the para-Kähler setting, so are the $\pm 1$-eigenspaces, which shows that any para-Kähler structure $(g, J)$ has necessarily an underlying Walker metric.

An almost hyper-paracomplex structure on a $4 n$-dimensional manifold $M$ is a triple $J_{a}, a=1,2,3$, where $J_{1}, J_{2}$ are almost paracomplex structures and $J_{3}$ is an almost complex structure, satisfying the paraquaternionic identities

$$
J_{1}^{2}=J_{2}^{2}=-J_{3}^{2}=1, \quad J_{1} J_{2}=-J_{2} J_{1}=J_{3}
$$

We note that on an almost hyper-paracomplex manifold there is actually a 2-sheeted hyperboloid of almost complex structures: $S_{1}^{2}(-1)=\left\{c_{1} J_{1}+c_{2} J_{2}+c_{3} J_{3}: c_{1}^{2}+c_{2}^{2}-c_{3}^{2}=-1\right\}$ and a 1 -sheeted hyperboloid of almost paracomplex structures: $S_{1}^{2}(1)=\left\{b_{1} J_{1}+b_{2} J_{2}+b_{3} J_{3}: b_{1}^{2}+b_{2}^{2}-b_{3}^{2}=1\right\}$. A hyper-paraHermitian metric is a pseudo-Riemannian metric which is compatible with the (almost) hyper-paracomplex structure in the sense that the metric $g$ is skew-symmetric with respect to each $J_{a}, a=1,2,3$, i.e.

$$
g\left(J_{1} ., J_{1} .\right)=g\left(J_{2} ., J_{2} .\right)=-g\left(J_{3} ., J_{3} .\right)=-g(., .) .
$$

Such a structure is called (almost) hyper-paraHermitian structure. If on a hyper-paraHermitian manifold there exists an admissible basis such that each $J_{a}, a=1,2,3$ is parallel with respect to the Levi-Civita connection or, equivalently, the three Kähler forms are closed, then the manifold is called hyper-symplectic [15]. In this case $J_{1}$ and $J_{2}$ are para-Kähler structures and it follows that $g$ is a Walker metric.

## Hypersurfaces with nilpotent shape operators

Einstein hypersurfaces $M$ in indefinite real space forms $\bar{M}(c)$ have been studied by Magid [17], who showed that the shape operator $S$ of any such hypersurface is diagonalizable, it defines, after rescaling, a complex structure on $M$ (i.e., $S^{2}=-b^{2} I d$ for some $b \neq 0$ ), or it is two-step nilpotent (i.e., $S^{2}=0$, $S \neq 0$ ). Since $S$ is a self-adjoint operator, its kernel is a completely degenerated subspace. Moreover the fact that $S$ is parallel shows that the underlying metric on $M$ is a Walker one [18].

## Four-dimensional Osserman metrics

Finally note that Walker metrics also appear associated with some curvature problems. Let $(M, g)$ be a pseudo-Riemannian metric of signature $(++--)$. Then, for each non-null vector $X$, the induced
metric on $X^{\perp}$ is of Lorentzian signature and thus the Jacobi operator $R_{X}=R(X, \cdot) X$, viewed as an endomorphism of $X^{\perp}$, corresponds to one of the following possibilities [4]:

$$
\left(\begin{array}{lll}
\alpha & & \\
& \beta & \\
& & \gamma
\end{array}\right), \quad\left(\begin{array}{ccc}
\alpha & -\beta & \\
\beta & \alpha & \\
& & \gamma
\end{array}\right), \quad\left(\begin{array}{lll}
\alpha & & \\
& \beta & \\
& 1 & \beta
\end{array}\right), \quad\left(\begin{array}{ccc}
\alpha & & \\
1 & \alpha & \\
& 1 & \alpha
\end{array}\right) .
$$

Type Ia
Type $I b$
Type II
Type III
Type Ia Osserman metrics correspond to real, complex and paracomplex space forms, Type Ib Osserman metrics do not exist [4] and Type II Osserman metrics with non-nilpotent Jacobi operators have recently been classified [9]. Further, note that any Type II Osserman metric whose Jacobi operators have nonzero eigenvalues is necessarily a Walker metric.

## 3 Proper almost complex structure

It is well-known that the existence of a metric of signature $(++--)$ with structure group $S O_{0}(2,2)$ is equivalent to the existence of a pair of commuting almost complex structures [19], and moreover, any such pseudo-Riemannian metric may be viewed as an indefinite almost Hermitian metric for a suitable almost complex structure. Such almost complex structures are not uniquely determined. One such structure associated with any four-dimensional Walker metric has been locally given in [20] and called the proper almost complex structure. Our purpose here is to investigate curvature properties of Walker metrics by considering the associated proper structure. It turns out that this structure exhibits a very rich behavior and provides examples of non-Kähler self-dual Einstein almost Kähler and Hermitian structures. It is important to recognize that such exceptional behavior comes from the fact that any proper almost Hermitian structure is isotropic Kähler but not necessarily Kähler.

Next, for a Walker metric (1) an orthonormal basis can be specialized by using the canonical coordinates as follows:

$$
\begin{array}{ll}
e_{1}=\frac{1}{2}(1-a) \partial_{x}+\partial_{z}, & e_{2}=-c \partial_{x}+\frac{1}{2}(1-b) \partial_{y}+\partial_{t}, \\
e_{3}=-\frac{1}{2}(1+a) \partial_{x}+\partial_{z}, & e_{4}=-c \partial_{x}-\frac{1}{2}(1+b) \partial_{y}+\partial_{t} . \tag{2}
\end{array}
$$

With respect to the local frame above, the metric is diagonal $[1,1,-1,-1]$, and hence a natural almost complex structure $J$ can be defined setting:

$$
J=e_{2} \otimes e^{1}-e_{1} \otimes e^{2}+e_{4} \otimes e^{3}-e_{3} \otimes e^{4}=\left(\begin{array}{cccc}
0 & -1 & 0 & 0 \\
1 & 0 & 0 & 0 \\
0 & 0 & 0 & -1 \\
0 & 0 & 1 & 0
\end{array}\right)
$$

This structure on a Walker 4-manifold, called proper in [20], induces a positive $\frac{\pi}{2}$-rotation on the degenerate parallel field $\mathcal{D}$ spanned by $\partial_{x}, \partial_{y}$. The proper almost complex structure is completely determined by the metric as follows [20]

$$
\begin{array}{ll}
J \partial_{x}=\partial_{y}, & J \partial_{z}=-c \partial_{x}+\frac{1}{2}(a-b) \partial_{y}+\partial_{t} \\
J \partial_{y}=-\partial_{x}, & J \partial_{t}=\frac{1}{2}(a-b) \partial_{x}+c \partial_{y}-\partial_{z} \tag{3}
\end{array}
$$

The space of linear invariants of an almost Hermitian manifold $\left(M^{n}, g, J\right)$ is given by $I_{n}=$ $\left\{\|\nabla \Omega\|^{2},\|d \Omega\|^{2},\|\delta \Omega\|^{2},\left\|N_{J}\right\|^{2}, \tau, \tau^{*}\right\}$, where

$$
\begin{array}{ll}
\|\nabla \Omega\|^{2}=\sum_{a, b, c=1}^{n} \varepsilon_{a} \varepsilon_{b} \varepsilon_{c}\left(\nabla_{e_{a}} \Omega\right)\left(e_{b}, e_{c}\right)^{2}, & \|d \Omega\|^{2}=\sum_{a, b, c=1}^{n} \varepsilon_{a} \varepsilon_{b} \varepsilon_{c} d \Omega\left(e_{a}, e_{b}, e_{c}\right)^{2} \\
\|\delta \Omega\|^{2}=\sum_{a=1}^{n} \varepsilon_{a} \delta \Omega\left(e_{a}\right)^{2}, & \left\|N_{J}\right\|^{2}=\sum_{a, b, c=1}^{n} \varepsilon_{a} \varepsilon_{b}\left\|N_{J}\left(e_{a}, e_{b}\right)\right\|^{2} \\
\tau=\sum_{a, b=1}^{n} \varepsilon_{a} \varepsilon_{b} R\left(e_{a}, e_{b}, e_{a}, e_{b}\right), & \tau^{*}=\frac{1}{2} \sum_{a, b=1}^{n} \varepsilon_{a} \varepsilon_{b} R\left(e_{a}, J e_{a}, e_{b}, J e_{b}\right)
\end{array}
$$

and $\left\{e_{1}, \ldots, e_{n}\right\}$ is a local orthonormal basis [14]. Further, note that if $(M, g, J)$ is four-dimensional, then $I_{4}=\left\{\|\nabla \Omega\|^{2},\left\|N_{J}\right\|^{2}, \tau, \tau^{*}\right\}$.

Recall that an indefinite almost Hermitian structure $(g, J)$ is said to be isotropic Kähler if $\|\nabla J\|^{2}$ $=0$ but $\nabla J \neq 0$. Examples of isotropic Kähler structures have been given first in [11] in dimension four and subsequently in [3] in dimension six. Our purpose in this section is to show that the class of isotropic Kähler structures is larger than expected. For instance, any proper almost Hermitian structure is so as follows.

Theorem 1 Any proper almost Hermitian structure $(g, J)$ on a Walker 4-manifold satisfies $\|\nabla \Omega\|^{2}=$ $0,\|d \Omega\|^{2}=0,\|\delta \Omega\|^{2}=0$ and $\left\|N_{J}\right\|^{2}=0$. Moreover, the scalar and $*$-scalar curvatures are given by $\tau=a_{x x}+b_{y y}+2 c_{x y}$ and $\tau^{*}=-a_{y y}-b_{x x}+2 c_{x y}$, respectively.
Proof. For the Nijenhuis tensor $N_{J}$ associated with $J$, put $N_{i j}=N_{J}\left(\partial_{i}, \partial_{j}\right)$. Then, after some calculations one has from (3) that

$$
\begin{aligned}
N_{x z}= & -N_{y t}=\frac{1}{2}\left(a_{x}-b_{x}-2 c_{y}\right) \partial_{x}+\frac{1}{2}\left(a_{y}-b_{y}+2 c_{x}\right) \partial_{y}, \\
N_{x t}= & N_{y z}=\frac{1}{2}\left(a_{y}-b_{y}+2 c_{x}\right) \partial_{x}-\frac{1}{2}\left(a_{x}-b_{x}-2 c_{y}\right) \partial_{y}, \\
N_{z t}= & \frac{1}{4}\left((a-b)\left(a_{y}-b_{y}+2 c_{x}\right)-2 c\left(a_{x}-b_{x}-2 c_{y}\right)\right) \partial_{x} \\
& -\frac{1}{4}\left((a-b)\left(a_{x}-b_{x}-2 c_{y}\right)+2 c\left(a_{y}-b_{y}+2 c_{x}\right)\right) \partial_{y} .
\end{aligned}
$$

Now, a straightforward calculation using the fact that the inverse of the metric tensor, $g^{-1}=\left(g^{\alpha \beta}\right)$ is given by

$$
g^{-1}=\left(\begin{array}{cccc}
-a & -c & 1 & 0 \\
-c & -b & 0 & 1 \\
1 & 0 & 0 & 0 \\
0 & 1 & 0 & 0
\end{array}\right)
$$

shows that $\left\|N_{J}\right\|^{2}=\sum_{i j k l} g^{i j} g^{k l} g\left(N_{i k}, N_{j l}\right)=0$.
The Levi-Civita connection of a Walker metric (1) is given by (see, for example, [9])

$$
\begin{array}{ll}
\nabla_{\partial_{x}} \partial_{z}=\frac{1}{2} a_{x} \partial_{x}+\frac{1}{2} c_{x} \partial_{y}, & \nabla_{\partial_{x}} \partial_{t}=\frac{1}{2} c_{x} \partial_{x}+\frac{1}{2} b_{x} \partial_{y}, \\
\nabla_{\partial_{y}} \partial_{z}=\frac{1}{2} a_{y} \partial_{x}+\frac{1}{2} c_{y} \partial_{y}, & \nabla_{\partial_{y}} \partial_{t}=\frac{1}{2} c_{y} \partial_{x}+\frac{1}{2} b_{y} \partial_{y}, \\
\nabla_{\partial_{z}} \partial_{z}=\frac{1}{2}\left(a a_{x}+c a_{y}+a_{z}\right) \partial_{x}+\frac{1}{2}\left(c a_{x}+b a_{y}-a_{t}+2 c_{z}\right) \partial_{y}-\frac{a_{x}}{2} \partial_{z}-\frac{a_{y}}{2} \partial_{t}, \\
\nabla_{\partial_{z}} \partial_{t}=\frac{1}{2}\left(a_{t}+a c_{x}+c c_{y}\right) \partial_{x}+\frac{1}{2}\left(b_{z}+c c_{x}+b c_{y}\right) \partial_{y}-\frac{c_{x}}{2} \partial_{z}-\frac{c_{y}}{2} \partial_{t}, \\
\nabla_{\partial_{t}} \partial_{t}=\frac{1}{2}\left(a b_{x}+c b_{y}-b_{z}+2 c_{t}\right) \partial_{x}+\frac{1}{2}\left(c b_{x}+b b_{y}+b_{t}\right) \partial_{y}-\frac{b_{x}}{2} \partial_{z}-\frac{b_{y}}{2} \partial_{t} .
\end{array}
$$

For the covariant derivative $\nabla J$ of the almost complex structure put $(\nabla J)_{i j}=\left(\nabla_{\partial_{i}} J\right) \partial_{j}$. Then, after
some calculations we obtain

$$
\begin{aligned}
(\nabla J)_{z x}= & \frac{1}{2}\left(a_{y}+c_{x}\right) \partial_{x}-\frac{1}{2}\left(a_{x}-c_{y}\right) \partial_{y}, \\
(\nabla J)_{z y}= & \frac{1}{2}\left(c_{y}-a_{x}\right) \partial_{x}-\frac{1}{2}\left(a_{y}+c_{x}\right) \partial_{y}, \\
(\nabla J)_{z z}= & \frac{1}{2}\left(a\left(a_{y}+c_{x}\right)-c\left(a_{x}-c_{y}\right)\right) \partial_{x}-\frac{1}{4}(a+b)\left(a_{x}-c_{y}\right) \partial_{y}-\frac{1}{2}\left(a_{y}+c_{x}\right) \partial_{z} \\
& +\frac{1}{2}\left(a_{x}-c_{y}\right) \partial_{t}, \\
(\nabla J)_{z t}= & \frac{1}{4}(a+b)\left(c_{y}-a_{x}\right) \partial_{x}-\frac{1}{2}\left(b\left(a_{y}+c_{x}\right)+c\left(a_{x}-c_{y}\right)\right) \partial_{y}+\frac{1}{2}\left(a_{x}-c_{y}\right) \partial_{z} \\
& +\frac{1}{2}\left(a_{y}+c_{x}\right) \partial_{t}, \\
(\nabla J)_{t x}= & \frac{1}{2}\left(b_{x}+c_{y}\right) \partial_{x}+\frac{1}{2}\left(b_{y}-c_{x}\right) \partial_{y}, \\
(\nabla J)_{t y}= & \frac{1}{2}\left(b_{y}-c_{x}\right) \partial_{x}-\frac{1}{2}\left(b_{x}+c_{y}\right) \partial_{y}, \\
(\nabla J)_{t z}= & \frac{1}{2}\left(a\left(b_{x}+c_{y}\right)+c\left(b_{y}-c_{x}\right)\right) \partial_{x}+\frac{1}{4}(a+b)\left(b_{y}-c_{x}\right) \partial_{y}-\frac{1}{2}\left(b_{x}+c_{y}\right) \partial_{z} \\
& -\frac{1}{2}\left(b_{y}-c_{x}\right) \partial_{t}, \\
(\nabla J)_{t t}= & \frac{1}{4}(a+b)\left(b_{y}-c_{x}\right) \partial_{x}-\frac{1}{2}\left(b\left(b_{x}+c_{y}\right)-c\left(b_{y}-c_{x}\right)\right) \partial_{y}-\frac{1}{2}\left(b_{y}-c_{x}\right) \partial_{z} \\
& +\frac{1}{2}\left(b_{x}+c_{y}\right) \partial_{t} .
\end{aligned}
$$

Now a long but straightforward calculation shows that

$$
\|\nabla J\|^{2}=\sum_{i, j, k, l} g^{i j} g^{k l} g\left((\nabla J)_{i k},(\nabla J)_{j l}\right)=0 .
$$

Then, it follows that $\|\nabla \Omega\|^{2}=\|d \Omega\|^{2}=\left\|N_{J}\right\|^{2}=0$ since for an arbitrary almost Hermitian 4-manifold, one has the identities

$$
\|\delta \Omega\|^{2}=\frac{1}{6}\|d \Omega\|^{2}, \quad\|\nabla \Omega\|^{2}=\frac{1}{3}\|d \Omega\|^{2}+\frac{1}{4}\left\|N_{J}\right\|^{2}
$$

Finally, the expressions of the scalar and *-scalar curvatures can be obtained by means of the formulas for the curvature tensor of a Walker metric given, for example, in [9], [20].

Remark 1 Examples of compact isotropic Kähler structures can be constructed on tori taking $a, b$ and $c$ in (1) to be periodic functions on $\mathbb{R}^{4}$. Moreover note that in the general situation the isotropic Kähler structures (1), (3) are neither complex nor symplectic. Indeed, according to [20], the proper almost Hermitian structure $(g, J)$ is :

- almost Kähler if and only if

$$
\begin{equation*}
a_{x}+b_{x}=0, \quad a_{y}+b_{y}=0 \tag{4}
\end{equation*}
$$

- Hermitian if and only if

$$
\begin{equation*}
a_{x}-b_{x}=2 c_{y}, \quad a_{y}-b_{y}=-2 c_{x} \tag{5}
\end{equation*}
$$

- Kähler if and only if

$$
\begin{equation*}
a_{x}=-b_{x}=c_{y}, \quad a_{y}=-b_{y}=-c_{x} . \tag{6}
\end{equation*}
$$

Hence, for special choices of functions (which may still be assumed to be periodic) satisfying (4) or (5) examples of symplectic or integrable isotropic Kähler structures can be given.

## 4 Almost Kähler self-dual proper structures

Considering the Riemann curvature tensor as an endomorphism of $\Lambda^{2}(M)$, we have the following $O(2,2)$-decomposition

$$
\begin{equation*}
R \equiv \frac{\tau}{12} I d_{\Lambda^{2}}+\rho_{0}+W: \Lambda^{2} \rightarrow \Lambda^{2} \tag{7}
\end{equation*}
$$

where $W$ denotes the Weyl conformal curvature tensor and $\rho_{0}$ the traceless Ricci tensor, $\rho_{0}(X, Y)$ $=\rho(X, Y)-\frac{\tau}{4} g(X, Y)$. The Hodge star operator $\star: \Lambda^{2} \rightarrow \Lambda^{2}$ associated to any $(++--)$-metric induces a further splitting $\Lambda^{2}=\Lambda_{+}^{2} \oplus \Lambda_{-}^{2}$, where $\Lambda_{ \pm}^{2}$ denotes the $\pm 1$-eigenspaces of the Hodge star operator, that is $\Lambda_{ \pm}^{2}=\left\{\alpha \in \Lambda^{2}(M) / \star \alpha= \pm \alpha\right\}$. Correspondingly, the curvature tensor decomposes as $R \equiv \frac{\tau}{12} I d_{\Lambda^{2}}+\rho_{0}+W^{+}+W^{-}$, where $W^{ \pm}=\frac{1}{2}(W \pm \star W)$. Recall that a pseudo-Riemannian 4 -manifold is called self-dual (resp., anti-self-dual) if $W^{-}=0$ (resp., $W^{+}=0$ ).

Let $\left\{e_{1}, e_{2}, e_{3}, e_{4}\right\}$ be the orthonormal basis given by (2). Then $\Lambda_{ \pm}^{2}=\left\langle\left\{E_{1}^{ \pm}, E_{2}^{ \pm}, E_{3}^{ \pm}\right\}\right\rangle$, where

$$
E_{1}^{ \pm}=\frac{e^{1} \wedge e^{2} \pm e^{3} \wedge e^{4}}{\sqrt{2}}, \quad E_{2}^{ \pm}=\frac{e^{1} \wedge e^{3} \pm e^{2} \wedge e^{4}}{\sqrt{2}}, \quad E_{3}^{ \pm}=\frac{e^{1} \wedge e^{4} \mp e^{2} \wedge e^{3}}{\sqrt{2}}
$$

Here observe that $e^{i} \wedge e^{j} \wedge \star\left(e^{k} \wedge e^{l}\right)=\left(\delta_{k}^{i} \delta_{l}^{j}-\delta_{l}^{i} \delta_{k}^{j}\right) \varepsilon_{i} \varepsilon_{j} e^{1} \wedge e^{2} \wedge e^{3} \wedge e^{4}$, where $\varepsilon_{i}=g\left(e_{i}, e_{i}\right)$. Further, note that $\left\langle E_{1}^{ \pm}, E_{1}^{ \pm}\right\rangle=1,\left\langle E_{2}^{ \pm}, E_{2}^{ \pm}\right\rangle=-1,\left\langle E_{3}^{ \pm}, E_{3}^{ \pm}\right\rangle=-1$, and therefore the self-dual and anti-self-dual Weyl curvature operators $W^{ \pm}: \Lambda_{ \pm}^{2} \longrightarrow \Lambda_{ \pm}^{2}$ have the following matrix form with respect to the bases above:

$$
W^{ \pm}=\left(\begin{array}{rrr}
W_{11}^{ \pm} & W_{12}^{ \pm} & W_{13}^{ \pm}  \tag{8}\\
-W_{12}^{ \pm} & -W_{22}^{ \pm} & -W_{23}^{ \pm} \\
-W_{13}^{ \pm} & -W_{23}^{ \pm} & -W_{33}^{ \pm}
\end{array}\right),
$$

where $W_{i j}^{ \pm}=W\left(E_{i}^{ \pm}, E_{j}^{ \pm}\right)$and $W\left(e^{i} \wedge e^{j}, e^{k} \wedge e^{l}\right)=W\left(e_{i}, e_{j}, e_{k}, e_{l}\right)$.
Self-dual Walker metrics have been previously investigated in [9] (see also [8]) showing that a metric (1) is self-dual if and only if the functions $a, b, c$ have the form

$$
\begin{align*}
& a(x, y, z, t)=x^{3} \mathcal{A}+x^{2} \mathcal{B}+x^{2} y \mathcal{C}+x y \mathcal{D}+x P+y Q+\xi \\
& b(x, y, z, t)=y^{3} \mathcal{C}+y^{2} \mathcal{E}+x y^{2} \mathcal{A}+x y \mathcal{F}+x S+y T+\eta  \tag{9}\\
& c(x, y, z, t)=\frac{1}{2} x^{2} \mathcal{F}+\frac{1}{2} y^{2} \mathcal{D}+x^{2} y \mathcal{A}+x y^{2} \mathcal{C}+\frac{1}{2} x y(\mathcal{B}+\mathcal{E})+x U+y V+\gamma
\end{align*}
$$

where all capital, calligraphic and Greek letters stand for arbitrary smooth functions depending only on the coordinates $(z, t)$.

Anti-self-dual Walker metrics are much more difficult to describe since the self-dual part of the Weyl curvature operator is given by

$$
W^{+}=\left(\begin{array}{ccc}
W_{11}^{+} & W_{12}^{+} & W_{11}^{+}+\frac{\tau}{12} \\
-W_{12}^{+} & \frac{\tau}{6} & -W_{12}^{+} \\
-W_{11}^{+}-\frac{\tau}{12} & -W_{12}^{+} & -W_{11}^{+}-\frac{\tau}{6}
\end{array}\right)
$$

where the expressions of $W_{11}^{+}$and $W_{12}^{+}$are as follows

$$
\begin{aligned}
& W_{11}^{+}=\frac{1}{12}( 6 c a_{x} b_{y}-6 a_{x} b_{z}-6 b a_{x} c_{y}+12 a_{x} c_{t}-6 c a_{y} b_{x}+6 a_{y} b_{t}+6 b a_{y} c_{x} \\
&+6 a_{z} b_{x}-6 a_{t} b_{y}-12 a_{t} c_{x}+6 a b_{x} c_{y}-6 a b_{y} c_{x}+12 b_{y} c_{z}-12 b_{z} c_{y} \\
&-a_{x x}-12 c^{2} a_{x x}-12 b c a_{x y}+24 c a_{x t}-3 b^{2} a_{y y}+12 b a_{y t}-12 a_{t t} \\
&-3 a^{2} b_{x x}+12 a b_{x z}-b_{y y}-12 b_{z z}+12 a c c_{x x}-2 c_{x y}+6 a b c_{x y} \\
&\left.-24 c c_{x z}-12 a c_{x t}-12 b c_{y z}+24 c_{z t}\right) \\
& \\
& W_{12}^{+}=\frac{1}{4}\left(a c_{x x}+a b_{x y}-b a_{x y}-b c_{y y}+2\left(a_{x t}-b_{y z}-c_{x z}+c_{y t}-c a_{x x}-c c_{x y}\right)\right) .
\end{aligned}
$$

Hence $W^{+}$has eigenvalues $\left\{\frac{\tau}{6},-\frac{\tau}{12},-\frac{\tau}{12}\right\}$ and, moreover, it is diagonalizable if and only if $\tau^{2}+$ $12 \tau W_{11}^{+}+48\left(W_{12}^{+}\right)^{2}=0($ cf. [9]).

Observe that the complex structure induces the opposite orientation to that defined by the Kähler form. (Indeed, the Kähler form corresponding to the proper almost Hermitian structure is $\Omega=\sqrt{2} E_{1}^{-}$).

Theorem 2 A proper almost Kähler structure $(g, J)$ on a Walker 4-manifold is self-dual if and only if

$$
\begin{align*}
a & =x y \mathcal{D}+x P+y Q+\xi \\
b & =-x y \mathcal{D}-x P-y Q+\eta  \tag{10}\\
c & =-\frac{1}{2} x^{2} \mathcal{D}+\frac{1}{2} y^{2} \mathcal{D}+x U+y V+\gamma
\end{align*}
$$

Proof. It is immediate from (4) and (9).

## 5 Almost Kähler *-Einstein proper structures

The $*$-Einstein equation $\left(\rho_{0}^{*}=\rho^{*}-\frac{\tau^{*}}{4} g=0\right)$ for a proper almost Hermitian structure can be written as a system of PDEs' as follows:

$$
\begin{align*}
\left(\rho_{0}^{*}\right)_{x z}= & -\left(\rho_{0}^{*}\right)_{y t}=-\left(\rho_{0}^{*}\right)_{z x}=\left(\rho_{0}^{*}\right)_{t y}=\frac{1}{4}\left(a_{y y}-b_{x x}\right)=0 \\
\left(\rho_{0}^{*}\right)_{x t}= & -\left(\rho_{0}^{*}\right)_{z y}=-\frac{1}{2}\left(a_{x y}-c_{x x}\right)=0 \\
\left(\rho_{0}^{*}\right)_{y z}= & -\left(\rho_{0}^{*}\right)_{t x}=-\frac{1}{2}\left(b_{x y}-c_{y y}\right)=0 \\
\left(\rho_{0}^{*}\right)_{z z}= & \frac{1}{4}\left\{a_{x} b_{x}+a_{y}\left(b_{y}-c_{x}\right)+b_{y} c_{x}+c_{y}\left(a_{x}-b_{x}\right)-c_{x}^{2}-c_{y}^{2}+2 c\left(a_{x y}-c_{x x}\right)\right. \\
& \left.+b a_{y y}-2 a_{y t}+a b_{x x}-2 b_{x z}-(a+b) c_{x y}+2 c_{x t}+2 c_{y z}\right\}=0  \tag{11}\\
\left(\rho_{0}^{*}\right)_{z t}= & -\frac{1}{4}\left\{(a-b)\left(a_{x y}-c_{x x}\right)+c\left(a_{y y}-b_{x x}\right)\right\}=0 \\
\left(\rho_{0}^{*}\right)_{t z}= & \frac{1}{4}\left\{(a-b)\left(b_{x y}-c_{y y}\right)+c\left(a_{y y}-b_{x x}\right)\right\}=0 \\
\left(\rho_{0}^{*}\right)_{t t}= & \frac{1}{4}\left\{a_{x} b_{x}+a_{y}\left(b_{y}-c_{x}\right)+b_{y} c_{x}+c_{y}\left(a_{x}-b_{x}\right)-c_{x}^{2}-c_{y}^{2}+2 c\left(b_{x y}-c_{y y}\right)\right. \\
& \left.+b a_{y y}-2 a_{y t}+a b_{x x}-2 b_{x z}-(a+b) c_{x y}+2 c_{x t}+2 c_{y z}\right\}=0 .
\end{align*}
$$

Note that the $*$-scalar curvature is given by

$$
\begin{equation*}
\tau^{*}=-a_{y y}-b_{x x}+2 c_{x y} \tag{12}
\end{equation*}
$$

Theorem 3 The proper almost Hermitian structure $(g, J)$ is almost Kähler and $*$-Einstein if and only if the functions $a, b$ and $c$ have the form

$$
\begin{align*}
a & =\left(x^{2}-y^{2}\right) \kappa+x P(z, t)+y Q(z, t)+\xi(z, t) \\
b & =\left(y^{2}-x^{2}\right) \kappa-x P(z, t)-y Q(z, t)+\eta(z, t)  \tag{13}\\
c & =2 x y \kappa+x U(z, t)+y V(z, t)+\gamma(z, t)
\end{align*}
$$

where $\kappa$ is a constant and

$$
\begin{equation*}
2\left(P_{z}+V_{z}-Q_{t}+U_{t}\right)=(P-V)^{2}+(Q+U)^{2}+4 \kappa(\xi+\eta) \tag{14}
\end{equation*}
$$

In this case the scalar and $*$-scalar curvatures are constant $\tau=\tau^{*}=8 \kappa$.
Proof. It follows from (4) and (11) that $(g, J)$ is almost Kähler and $*$ - Einstein if and only if

$$
\begin{gather*}
a_{x}+b_{x}=a_{y}+b_{y}=0  \tag{15}\\
a_{x y}=c_{x x}, \quad b_{x y}=c_{y y}, \quad a_{y y}=b_{x x}
\end{gather*}
$$

and

$$
\begin{align*}
& a_{x} b_{x}+a_{y} b_{y}-a_{y} c_{x}+b_{y} c_{x}+a_{x} c_{y}-b_{x} c_{y}-c_{x}^{2}-c_{y}^{2}+2 c a_{x y}+b a_{y y} \\
& -2 a_{y t}+a b_{x x}-2 b_{x z}-2 c c_{x x}-(a+b) c_{x y}+2 c_{x t}+2 c_{y z}=0 \tag{16}
\end{align*}
$$

Using (15) we easily get that

$$
a+b=T(z, t), \quad c_{x x}=a_{x y}=-c_{y y}, \quad a_{x x}+a_{y y}=0
$$

where $T$ is a smooth function depending only on $z$ and $t$. Hence $c_{x}=a_{y}+A(y, z, t), c_{y}=-a_{x}+$ $B(x, z, t)$ for some smooth functions $A, B$, and the equation $a_{x x}+a_{y y}=0$ implies that $A_{y}=B_{x}$. Thus

$$
A(y, z, t)=y \alpha(z, t)+\beta(z, t), \quad B(x, z, t)=x \alpha(z, t)+\delta(z, t)
$$

where $\alpha, \beta, \delta$ are smooth functions. Therefore the system (15) is equivalent to

$$
\begin{gather*}
c_{x}=a_{y}+y \alpha(z, t)+\beta(z, t), \quad c_{y}=-a_{x}+x \alpha(z, t)+\delta(z, t),  \tag{17}\\
a_{x x}+a_{y y}=0, \quad b=T(z, t)-a .
\end{gather*}
$$

Now a straightforward computation making use of (17) shows that the condition (16) can be written as

$$
\begin{equation*}
\left(2 a_{y}+y \alpha+\beta\right)^{2}+\left(2 a_{x}-x \alpha-\delta\right)^{2}=2 x \alpha_{z}+2 y \alpha_{t}+2 \delta_{z}+2 \beta_{t}-\alpha T \tag{18}
\end{equation*}
$$

Set

$$
\begin{equation*}
H(x, y, z, t)=2 a(x, y, z, t)-\frac{1}{2}\left(x^{2}-y^{2}\right) \alpha(z, t)-x \delta(z, t)+y \beta(z, t) \tag{19}
\end{equation*}
$$

Then (18) takes the form

$$
\begin{equation*}
H_{x}^{2}+H_{y}^{2}=2 x \alpha_{z}+2 y \alpha_{t}+2 \delta_{z}+2 \beta_{t}-\alpha T . \tag{20}
\end{equation*}
$$

The latter identity shows that, for any fixed $z$ and $t$, the right-hand side of (20) is a non-negative linear function of $x$ and $y$. This implies that the coefficients $\alpha_{z}$ and $\alpha_{t}$ vanish, i.e. the function $\alpha(z, t)$ is constant. Moreover, using the fact that $a_{x x}+a_{y y}=0$ (cf. (17)) we get from (19) that

$$
\begin{equation*}
H_{x x}+H_{y y}=0 \tag{21}
\end{equation*}
$$

Now we shall show that

$$
H_{x x}=H_{x y}=H_{y y}=0 .
$$

Indeed, differentiating (20) in $x$ and $y$ gives, in view of (21), that

$$
H_{x} H_{x x}+H_{y} H_{x y}=0 \quad-H_{y} H_{x x}+H_{x} H_{x y}=0 .
$$

Therefore

$$
\begin{equation*}
\left(H_{x}^{2}+H_{y}^{2}\right) H_{x x}=\left(H_{x}^{2}+H_{y}^{2}\right) H_{x y}=0 \tag{22}
\end{equation*}
$$

Suppose $H_{x x}\left(x_{0}, y_{0}, z_{0}, t_{0}\right) \neq 0$ at some point $\left(x_{0}, y_{0}, z_{0}, t_{0}\right)$. Then $H_{x x} \neq 0$ on a neighborhood $\mathfrak{U}$ of this point and (22) implies that $H_{x}=0$ on $\mathfrak{U}$, hence $H_{x x}\left(x_{0}, y_{0}, z_{0}, t_{0}\right)=0$, a contradiction. Thus $H_{x x}=H_{x y}=H_{y y}=0$, therefore $H$ is a linear function in $x$ and $y$, say

$$
H=x p(z, t)+y q(z, t)+2 \xi(z, t)
$$

Then it follows from (21) that

$$
\begin{equation*}
a=\frac{1}{4}\left(x^{2}-y^{2}\right) \alpha+\frac{1}{2} x(p+\delta)+\frac{1}{2} y(q-\beta)+\xi \tag{23}
\end{equation*}
$$

and (20) gives

$$
\begin{equation*}
p^{2}+q^{2}=2 \delta_{z}+2 \beta_{t}-\alpha T \tag{24}
\end{equation*}
$$

Now, integrating the system (17) for $c$, we obtain that

$$
\begin{equation*}
c=\frac{1}{2} x y \alpha+\frac{1}{2} x(q+\beta)-\frac{1}{2} y(p-\delta)+\gamma, \tag{25}
\end{equation*}
$$

where $\gamma$ is a smooth function depending only on $z$ and $t$. Setting

$$
4 \kappa=\alpha, \quad 2 P=p+\delta, \quad 2 Q=q-\beta, \quad 2 U=q+\beta, \quad 2 V=-p+\delta, \quad \eta=T-\xi
$$

we see from (23), (24) and (25) that the functions $a, b$ and $c$ have the form (13).
Let $\tau$ and $\tau^{*}$ be the scalar and $*$-scalar curvature. Then, it follows from (21) and Theorem 1 that $\tau=\tau^{*}=8 \kappa=$ const.

Corollary 4 The proper almost Hermitian structure $(g, J)$ is almost Kähler, self-dual and $*$-Einstein if and only if the functions $a, b$ and $c$ have the form (13)-(14) with $\kappa=0$.

Corollary 5 If the function a (resp. b) depends only on $(z, t)$, then the structure $(g, J)$ is almost Kähler and $*$-Einstein if and only if the function b (resp. a) depends only on ( $z, t$ ) and the function c has the form

$$
c=x U(z, t)+y V(z, t)+\gamma(z, t)
$$

where

$$
2\left(V_{z}+U_{t}\right)=V^{2}+U^{2}
$$

Corollary 6 If the function $c$ depends only on $(z, t)$, then the structure $(g, J)$ is almost Kähler and *-Einstein if and only if the functions $a$ and $b$ have the form

$$
\begin{align*}
& a=x P(z, t)+y Q(z, t)+\xi(z, t) \\
& b=-x P(z, t)-y Q(z, t)+\eta(z, t) \tag{26}
\end{align*}
$$

where

$$
\begin{equation*}
2\left(P_{z}-Q_{t}\right)=P^{2}+Q^{2} \tag{27}
\end{equation*}
$$

## 6 Almost Kähler Einstein proper structures

The Einstein equation for a Walker metric (1) is a system of PDEs' as follows (cf. [20]):

$$
\begin{align*}
\left(\rho_{0}\right)_{x z}= & -\left(\rho_{0}\right)_{y t}=\left(\rho_{0}\right)_{z x}=-\left(\rho_{0}\right)_{t y}=\frac{1}{4}\left(a_{x x}-b_{y y}\right)=0, \\
\left(\rho_{0}\right)_{x t}= & \left(\rho_{0}\right)_{t x}=\frac{1}{2}\left(b_{x y}+c_{x x}\right)=0, \\
\left(\rho_{0}\right)_{y z}= & \left(\rho_{0}\right)_{z y}=\frac{1}{2}\left(a_{x y}+c_{y y}\right)=0, \\
\left(\rho_{0}\right)_{z z}= & \frac{1}{4} a a_{x x}+c a_{x y}+\frac{1}{2} b a_{y y}-a_{y t}+c_{y z}-\frac{1}{2} a_{y} c_{x} \\
& +\frac{1}{2} a_{x} c_{y}+\frac{1}{2} a_{y} b_{y}-\frac{1}{2} c_{y}^{2}-\frac{1}{2} a c_{x y}-\frac{1}{4} a b_{y y}=0,  \tag{28}\\
\left(\rho_{0}\right)_{z t}= & \left(\rho_{0}\right)_{t z}=\frac{1}{2} a c_{x x}+\frac{1}{2} c c_{x y}+\frac{1}{2} a_{x t}-\frac{1}{2} c_{x z}-\frac{1}{2} a_{y} b_{x}+\frac{1}{2} c_{x} c_{y} \\
& \quad+\frac{1}{2} b c_{y y}-\frac{1}{2} c_{y t}+\frac{1}{2} b_{y z}-\frac{1}{4} c a_{x x}-\frac{1}{4} c b_{y y}=0, \\
\left(\rho_{0}\right)_{t t}= & \frac{1}{2} a b_{x x}+c b_{x y}+c_{x t}-b_{x z}-\frac{1}{2} c_{x}^{2}+\frac{1}{2} a_{x} b_{x} \\
& \quad-\frac{1}{2} b_{x} c_{y}+\frac{1}{2} b_{y} c_{x}+\frac{1}{4} b b_{y y}-\frac{1}{4} b a_{x x}-\frac{1}{2} b c_{x y}=0 .
\end{align*}
$$

Note that the scalar curvature is given by

$$
\begin{equation*}
\tau=a_{x x}+b_{y y}+2 c_{x y} \tag{29}
\end{equation*}
$$

Theorem 7 The structure $(g, J)$ is strictly almost Kähler Einstein if and only if the functions $a, b$ and $c$ have the form

$$
\begin{align*}
& a=x P(z, t)+y Q(z, t)+\xi(z, t), \\
& b=-x P(z, t)-y Q(z, t)+\eta(z, t)  \tag{30}\\
& c=x U(z, t)+y V(z, t)+\gamma(z, t),
\end{align*}
$$

where

$$
\begin{align*}
& 2\left(V_{z}-Q_{t}\right)=V^{2}-V P+Q^{2}+U Q, \\
& 2\left(P_{z}+U_{t}\right)=P^{2}-V P+U^{2}+U Q,  \tag{31}\\
& Q_{z}+U_{z}-P_{t}+V_{t}=P Q+U V,
\end{align*}
$$

and $(V-P)^{2}+(U+Q)^{2} \not \equiv 0$.
Proof. It follows from (4) that the structure $(g, J)$ is almost Kähler Einstein if and only if

$$
\begin{equation*}
a_{x}+b_{x}=a_{y}+b_{y}=0, \quad a_{x y}+c_{y y}=b_{x y}+c_{x x}=0, \quad a_{x x}=b_{y y} \tag{32}
\end{equation*}
$$

and

$$
\begin{align*}
& b a_{y y}+2 c a_{x y}-a c_{x y}-2 a_{y t}+2 c_{y z}+a_{y} b_{y}+a_{x} c_{y}-a_{y} c_{x}-c_{y}^{2}=0 \\
& a b_{x y}+b a_{x y}+c a_{x x}-c c_{x y}-a_{x t}-b_{y z}+c_{y t}+c_{x z}+a_{y} b_{x}-c_{x} c_{y}=0  \tag{33}\\
& a b_{x x}+2 c b_{x y}-b c_{x y}-2 b_{x z}+2 c_{x t}+a_{x} b_{x}-b_{x} c_{y}+c_{x} b_{y}-c_{x}^{2}=0
\end{align*}
$$

It is easy to see that equation (32) implies (15). Moreover adding up the first and the third equations of (33) we get (16). Hence the structure $(g, J)$ is $*$-Einstein and the functions $a, b, c$ have the form (13). Plugging the expressions (13) for $a, b, c$ into the first equation of (33) and comparing the coefficients of the variables $x$ and $y$, we get $\kappa(Q+U)=\kappa(P-V)=0$. It follows that $\kappa=0$ since otherwise $Q+U=P-V=0$ which implies, by (6), that the structure $(g, J)$ is Kähler. Thus the functions $a, b, c$ have the form (30). Now it is easy to check that the system (33) takes the form (31).

Corollary 8 Any proper strictly almost Kähler Einstein structure is self-dual, Ricci flat and *-Ricci flat.

Corollary 9 If the function $c$ depends only on $(z, t)$, the structure $(g, J)$ is strictly almost Kähler Einstein if and only if the functions $a$ and $b$ have the form

$$
\begin{align*}
& a=x P(z, t)+y Q(z, t)+\xi(z, t) \\
& b=-x P(z, t)-y Q(z, t)+\eta(z, t) \tag{34}
\end{align*}
$$

where

$$
\begin{equation*}
2 P_{z}=P^{2}, \quad 2 Q_{t}=-Q^{2}, \quad Q_{z}-P_{t}=P Q \tag{35}
\end{equation*}
$$

and $P^{2}+Q^{2} \not \equiv 0$.
Remark 2 i) In a neighborhood of a point where $P \neq 0$ and $Q \neq 0$ the solution of the system (35) is given by

$$
\begin{equation*}
P=\frac{2 p}{t-p z+q}, \quad Q=\frac{2}{t-p z+q}, \tag{36}
\end{equation*}
$$

where $p, q$ are non-zero constants.
ii) In a neighborhood of a point where $P \neq 0$ and $Q=0$ the solution of the system (35) is given by

$$
\begin{equation*}
P=-\frac{2}{z+q}, \tag{36}
\end{equation*}
$$

where $q$ is a non-zero constant. It should be noted that this family of solutions contains the first counterexample, due to Haze (see [20]), to the Goldberg conjecture of indefinite and noncompact type.

Corollary 10 If the function a (resp. b) depends only on $(z, t)$, then the structure $(g, J)$ is strictly almost Kähler Einstein if and only if the function b (resp. a) depends only on ( $z, t$ ) and the function c has the form

$$
\begin{equation*}
c=x U(z, t)+y V(z, t)+\gamma(z, t) \tag{37}
\end{equation*}
$$

where

$$
\begin{equation*}
2 U_{t}=U^{2}, \quad 2 V_{z}=V^{2}, \quad U_{z}+V_{t}=U V \tag{38}
\end{equation*}
$$

and $U^{2}+V^{2} \not \equiv 0$.

Remark 3 In a neighbourhood of a point where $U \neq 0$ and $V \neq 0$ the solution of the system (38) is given by

$$
\begin{equation*}
U=-\frac{2}{t+p z+q}, \quad V=-\frac{2 p}{t+p z+q} \tag{39}
\end{equation*}
$$

where $p, q$ are non-zero constants.
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