# LOOKING FOR A NATURAL NOTION OF SUPERSPACE<sup>†</sup>

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Why Lie superalgebras?

Where are they?

(A very familiar example from differential geometry)

Classification problems

Application: Natural 3D-superspaces

Definition. A Lie algebra is a vector space g

$$[\,\cdot\,,\,\cdot\,]:\mathfrak{g} imes\mathfrak{g} o\mathfrak{g}$$

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satisfying Jacobi identity

(J0) 
$$[x, [y, z]] + [z, [x, y]] + [y, [z, x]] = 0$$

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**Definition.** A **representation** of a Lie algebra  $\mathfrak{g}$  on a vector space V is a linear map  $\rho : \mathfrak{g} \to \mathfrak{gl}(V)$ , satisfying,

$$\rho([x,y]) = [\rho(x), \rho(y)]$$

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Why Lie superalgebras?

Roughly: To bring symmetric maps in,....

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$$\Longrightarrow \Gamma := [\![\cdot,\cdot]\!]|_{\mathfrak{g}_1 \times \mathfrak{g}_1}$$
 is symmetric

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and for any x, y, and z in Dom $|\cdot|$ ,

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$$\Rightarrow$$
  $[x + u, y + v] = [x, y] + \rho(x)(v) - \rho(y)u + \Gamma(u, v)$ 

**Proposition.** A Lie superalgebra is a triple  $(\mathfrak{g}_{\mathfrak{o}}, \rho, \Gamma)$  consisting of: (a) A Lie algebra  $[\cdot, \cdot] : \mathfrak{g}_{0} \times \mathfrak{g}_{0} \to \mathfrak{g}_{0}$ ,

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and  $\forall u, v, w \in \mathfrak{g}_1$ ,

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**Remark.** Under certain circumstances (J1)  $\Longrightarrow$  (J2).

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**Proposition.** This is the case when  $\rho = ad$ .

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Within this context, one writes  $\mathfrak{g} = \mathfrak{gl}(V_0|V_1)$  to distinguish it from  $\mathfrak{gl}(V_0 \oplus V_1)$ .

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**Moral.** End $(V_0 \oplus V_1)$  admits both structures.

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$$\Omega^0(M) = C^{\infty}(M), \qquad \Omega^1(M) = \Gamma(T^*M), \qquad \Omega^2(M) = \Gamma(\Lambda^2 T^*M),$$

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Thus obtain a Lie superalgebra  $\mathfrak{g} = (\mathbb{R} \Delta) \oplus (\mathbb{R} d \oplus \mathbb{R} \delta)$  embedded in  $\mathfrak{gl}(\Omega(M)_0|\Omega(M)_1)$ , where

$$\Omega(M)_0 = \bigoplus_{k \ge 0} \Omega^{2k}(M), \quad \text{and} \quad \Omega(M)_1 = \bigoplus_{k \ge 0} \Omega^{2k+1}(M)$$

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Furthermore,

$$\mathcal{L}_X := [\![ d, i_X ]\!] = d \circ i_X - (-1)^{1 \cdot 1} i_X \circ d : \Omega^k(M) \to \Omega^k(M)$$

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which together  $[\![d, \mathcal{L}_X]\!] = 0$  and  $[\![d, d]\!] = 0$ , yield more Lie superalgebras embedded in  $\mathfrak{gl}(\Omega(M)_0|\Omega(M)_1)$ .

Let  $V = V_0 \oplus V_1$  be a *complex* supervector space, and let

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To keep track of their type of symmetry, write

$$B_{\alpha}(v, w) = \varepsilon_{\alpha} B_{\alpha}(w, v), \qquad \varepsilon_{\alpha} = \begin{cases} +1 & \text{if } B_{\alpha} \text{ symmetric} \\ -1 & \text{if } B_{\alpha} \text{ skew-symmetric} \end{cases}$$

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Define a nondegenerate bilinear form B on  $V = V_0 \oplus V_1$ :

$$B(v_0 + v_1, w_0 + w_1) := B_0(v_0, w_0) + B_1(v_1, w_1)$$

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Establish the identification,

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$$S \leftrightarrow \begin{pmatrix} \alpha & \beta \\ \gamma & \delta \end{pmatrix}$$
, so that,  $S \begin{pmatrix} v_0 \\ v_1 \end{pmatrix} = \begin{pmatrix} \alpha(v_0) + \beta(v_1) \\ \gamma(v_0) + \delta(v_1) \end{pmatrix}$ .

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Besides,  $B_1(w, \gamma(u)) = -B_0(\beta(w), u)$  is satisfied if and only if, either  $\gamma \equiv 0 \equiv \beta$ , or else  $\varepsilon_{B_0} \varepsilon_{B_1} = 1$ .

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**Remark.** Let  $v_0 \in V_0$ , and  $v_1 \in V_1$ . Put  $\gamma = B_0(v_0, \cdot) v_1 \in \text{Hom}(V_0, V_1)$ . **Remark.** Let  $v_0 \in V_0$ , and  $v_1 \in V_1$ . Put  $\gamma = B_0(v_0, \cdot) v_1 \in \text{Hom}(V_0, V_1)$ .

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**Moral.** The Lie algebra  $\mathfrak{g}_B(V_0 \oplus V_1)$  likes  $\varepsilon_{B_0} \varepsilon_{B_1} = 1$  to describe the linear transformations that preserve the nondegenerate bilinear form

$$B(v_0 + v_1, w_0 + w_1) := B_0(v_0, w_0) + B_1(v_1, w_1)$$

whereas the Lie superalgebra  $\mathfrak{g}_B(V_0|V_1)$  likes  $\varepsilon_{B_0}\varepsilon_{B_1}=-1$ .

Recall that a Lie superalgebra is a triple  $(\mathfrak{g}_{o}, \rho, \Gamma)$  consisting of:

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- (a) A Lie algebra  $[\cdot, \cdot]: \mathfrak{g}_0 \times \mathfrak{g}_0 \to \mathfrak{g}_0$ ,
- (b) A representation  $\rho: \mathfrak{g}_0 \to \mathfrak{gl}(\mathfrak{g}_1)$ ,
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(J1) 
$$[x, \Gamma(u, v)] = \Gamma(\rho(x)u, v) + \Gamma(u, \rho(x)v)$$

for any  $x \in \mathfrak{g}_0$  and any u, and v in  $\mathfrak{g}_1$ 

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for any  $x \in \mathfrak{g}_0$  and any u, and v in  $\mathfrak{g}_1$ , and

(J2) 
$$\rho\left(\Gamma(u,v)\right)(w) + \rho\left(\Gamma(w,u)\right)(v) + \rho\left(\Gamma(v,w)\right)(u) = 0$$

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#### Classification problems.

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**Recall.** Under certain circumstances  $(J1) \Longrightarrow (J2)$ .

**Proposition.** This is the case when  $\rho = ad$ .

$$([\cdot,\cdot],\rho,\Gamma)\simeq([\cdot,\cdot]',\rho',\Gamma')$$

if and only if

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$$[\cdot, \cdot]' = T[T^{-1}(\cdot), T^{-1}(\cdot)]$$

$$\rho' = S \circ \rho(T^{-1}(\cdot)) \circ S^{-1}$$

$$\Gamma' = T(\Gamma(S^{-1}(\cdot), S^{-1}(\cdot)))$$

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When  $[\cdot, \cdot]$  is kept fixed in  $\mathfrak{g}_0$ , and  $\rho = \mathrm{ad}$ ,

$$G = \{ (T, S) \mid [\operatorname{ad}(\cdot), T \circ S^{-1}] = 0 \} \subset \operatorname{Aut}(\mathfrak{g}_0) \times \operatorname{GL}(\mathfrak{g}_0)$$

since  $\operatorname{ad}(T^{-1}(x)) = T^{-1} \circ \operatorname{ad}(x) \circ T$ .

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To classify the different Lie superalgebras on  $\mathfrak{g}_0$  with  $[\cdot, \cdot]$  fixed and  $\rho = \operatorname{ad}$ , amounts to parametrize the orbits in  $\operatorname{Sym}_{\operatorname{ad}}(\mathfrak{g}_0)$  under the left G-action

$$\Gamma \mapsto (T, S) \cdot \Gamma = T(\Gamma(S^{-1}(\cdot), S^{-1}(\cdot)))$$

**Application.** Spacetime is conveniently identified —locally, at least— with the Lie algebra  $\mathfrak{u}_2 = \text{Lie}(U(2))$ . In fact,

$$x \in \mathfrak{u}_2 \Leftrightarrow x = i \begin{pmatrix} x_0 + x_3 & x_1 - ix_2 \\ x_1 + ix_2 & x_0 - x_3 \end{pmatrix}; \quad \det(x) = x_1^2 + x_2^2 + x_3^2 - x_0^2$$

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**Project:** Apply the classification to  $\mathfrak{g}_0 = \mathfrak{u}_2$  to understand what the **natural** possibilities for super-spacetimes might be.

**Strategy:** Note first that  $\mathfrak{u}_2$  is a **real subalgebra** of  $\mathfrak{gl}_2(\mathbb{C})$ . Thus, apply the classification scheme first to  $\mathfrak{gl}_2(\mathbb{C})$ .

Consider the following basis of  $\mathfrak{gl}_2(\mathbb{C})$ :

$$x_0 := I = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \qquad x_1 := H = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix},$$
 $x_2 := E = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \qquad x_3 := F = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}.$ 

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and the following basis of  $\mathfrak{u}_2$ :

$$w_0 := iI = \begin{pmatrix} i & 0 \\ 0 & i \end{pmatrix}, \qquad w_3 := iH = \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix},$$
$$w_2 := E - F = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}, \qquad w_1 := i(E + F) = \begin{pmatrix} 0 & i \\ i & 0 \end{pmatrix}.$$

**Proposition.** The space  $\operatorname{Sym}_{\operatorname{ad}}(\mathfrak{gl}_2(\mathbb{C}))$  depends on three complex parameters  $(\lambda, \mu, \nu)$  in such a way that  $\Gamma : \mathfrak{gl}_2(\mathbb{C}) \times \mathfrak{gl}_2(\mathbb{C}) \to \mathfrak{gl}_2(\mathbb{C})$  is given by,

$$\begin{split} &\Gamma(x_0,x_0) = \lambda x_0 \\ &\Gamma(x_0,x_1) = \mu x_1 \quad \Gamma(x_1,x_1) = 2\nu x_0 \\ &\Gamma(x_0,x_2) = \mu x_2 \quad \Gamma(x_1,x_2) = 0 \qquad \quad \Gamma(x_2,x_2) = 0 \\ &\Gamma(x_0,x_3) = \mu x_3 \quad \Gamma(x_1,x_3) = 0 \qquad \quad \Gamma(x_2,x_3) = \nu x_0 \quad \Gamma(x_3,x_3) = 0. \end{split}$$

A similar statement holds true for  $\mathfrak{gl}_2(\mathbb{R})$ .

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**Note.** Note that a different symmetric bilinear map  $\Gamma'$ :  $\mathfrak{gl}_2 \times \mathfrak{gl}_2 \to \mathfrak{gl}_2$  would yield a different set of parameters; say  $\lambda'$ ,  $\mu'$  and  $\nu'$ , respectively.

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**Notation.** Let us denote by  $\mathfrak{gl}_2(\lambda, \mu, \nu)$  the  $\mathbb{F}$ -Lie superalgebra (with  $\mathbb{F}$  either  $\mathbb{C}$  or  $\mathbb{R}$ )  $\mathfrak{gl}_2 \oplus \mathfrak{gl}_2$  defined by the parameter values  $(\lambda, \mu, \nu)$ .

**Theorem.**  $\mathfrak{gl}_2(\lambda, \mu, \nu) \simeq \mathfrak{gl}_2(\lambda', \mu', \nu')$  are isomorphic if and only there are nonzero constants a, b and c in the ground field  $\mathbb{F}$ , such that,

$$\lambda' = \lambda \frac{1}{ab^2}, \qquad \mu' = \mu \frac{1}{abc}, \qquad \nu' = \nu \frac{a}{c^2}.$$

In particular, there are exactly eight different isomorphism classes of such Lie superalgebras when the ground field is  $\mathbb{C}$ , whereas there are ten when the ground field is  $\mathbb{R}$ , since the sign of the product  $\lambda \nu$  must be preserved.

For the real Lie superalgebras  $\mathfrak{u}_2(\lambda,\mu,\nu)$  whose underlying supervector space is  $\mathfrak{u}_2 \oplus \mathfrak{u}_2$ , use the basis  $w_0 = iI$ ,  $w_3 = iH$ ,  $w_2 = E - F$  and  $w_1 = i(E + F)$ , to get:

$$\Gamma(w_0, w_0) = i\lambda w_0$$

$$\Gamma(w_0, w_3) = i\mu w_3 \quad \Gamma(w_3, w_3) = 2i\nu w_0$$

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Therefore,  $\lambda$ ,  $\mu$  and  $\nu$  have to be restricted, from taking arbitrary complex values in  $\mathfrak{gl}_2(\mathbb{C}; \lambda, \mu, \nu)$ , to take only purely imaginary values on  $\mathfrak{u}_2(\lambda, \mu, \nu)$ .

Notation: Write,  $\mathfrak{g}_0 = \operatorname{Span}\{e_1, e_2, e_3\}$ , and

$$[e_1, e_2] = ae_2 + ce_3,$$
  
 $[e_1, e_3] = be_2 + de_3, \Rightarrow \operatorname{ad}(e_1)|_{\mathfrak{g}'_0} \leftrightarrow A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$   
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**Prop.** Let  $\mathfrak{g}_0 = \mathfrak{g}_1$  be 3-dimensional, with  $\rho = \operatorname{ad}$ . Set  $\mathfrak{g}'_0 = [\mathfrak{g}_0, \mathfrak{g}_0]$ . Then,

$$\dim \mathfrak{g}_0' \qquad \qquad 3 \qquad \qquad 2 \qquad \qquad 1 \qquad \qquad 0$$

$$\dim \operatorname{Sym}_{\operatorname{ad}}(\mathfrak{g}_0) \qquad 0 \qquad 1 \qquad 5 \qquad 18$$

 $\mathfrak{g}_0$ 

$$\dim \mathfrak{g}_0'$$

A

Constraints

 $\mathfrak{p}(\mathbb{F})$ 

$$\left(\begin{array}{cc} 1 & 1 \\ 0 & 1 \end{array}\right)$$

 $\mathfrak{q}_{\lambda}(\mathbb{F})$ 

$$\begin{pmatrix} 1 & 0 \\ 0 & \lambda \end{pmatrix}$$

$$0 < |\lambda| \le 1$$

 $\mathfrak{q}^1_\lambda(\mathbb{R})$ 

$$2 \qquad \left( \begin{array}{c} \lambda & -1 \\ 1 & \lambda \end{array} \right)$$

$$\lambda \in \mathbb{R}$$

 $\mathfrak{q}_0(\mathbb{F})$ 

$$\left( \begin{smallmatrix} 1 & 0 \\ 0 & 0 \end{smallmatrix} \right)$$

 $\mathfrak{h}(\mathbb{F})$ 

$$\begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$$

 $\mathfrak{a}(\mathbb{F})$ 

$$\left(\begin{smallmatrix}0&0\\0&0\end{smallmatrix}\right)$$

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- 3.  $\exists$  3 (real) based on  $\mathfrak{q}_{\lambda}^1(\mathbb{R})$ .
- 4.  $\exists$  13 (resp., 20) based on  $\mathfrak{q}_0(\mathbb{C})$  (resp.,  $\mathfrak{q}_0(\mathbb{R})$ ), plus a non-zero-parameter family (resp., two (non-zero)-one-parameter families) based on  $\mathfrak{q}_0(\mathbb{C})$  (resp.,  $\mathfrak{q}_0(\mathbb{R})$ ).

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#### Sketch of The Proofs

**Lemma.** Let  $\mathbb{F}$  be either  $\mathbb{R}$  or  $\mathbb{C}$ , and let  $\dot{\mathbb{F}} = \mathbb{F} - \{0\}$ . The set of pairs  $(T, S) \in \operatorname{Aut}(\mathfrak{gl}_n) \times \operatorname{GL}(\mathfrak{gl}_n)$  such that [T(x), S(y)] = S([x, y]), with the group structure inherited from the direct product  $\operatorname{Aut}(\mathfrak{gl}_n) \times \operatorname{GL}(\mathfrak{gl}_n)$ , is isomorphic to the direct product  $\operatorname{group} \dot{\mathbb{F}} \times \dot{\mathbb{F}} \times \dot{\mathbb{F}} \times \operatorname{Aut}(\mathfrak{sl}_n)$ .

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*Proof.* Use the fact  $\mathfrak{g} = \mathfrak{gl}_n = \langle I_n \rangle \oplus \mathfrak{sl}_n$ , to see that:

(1)  $T \in \operatorname{Aut}(\mathfrak{gl}_n)$  if and only if  $\exists a \in \dot{\mathbb{F}}$  and  $t \in \operatorname{Aut}(\mathfrak{sl}_n)$ 

$$T = \begin{pmatrix} a & 0 \\ 0 & t \end{pmatrix}$$

(2) For any  $x \in \mathfrak{gl}_n$ ,

$$ad(x) = \begin{pmatrix} 0 & 0 \\ 0 & ad(x)|_{\mathfrak{sl}_n} \end{pmatrix}$$

(3)  $T^{-1} \circ S$  commutes with ad(x) if and only if

$$T^{-1} \circ S = \begin{pmatrix} b & 0 \\ 0 & u \end{pmatrix}$$

for some  $b \in \dot{\mathbb{F}}$ , and  $u \in GL(\mathfrak{sl}_n)$  such that  $u \circ (\operatorname{ad}(x)|_{\mathfrak{sl}_n}) = (\operatorname{ad}(x)|_{\mathfrak{sl}_n}) \circ u$ .

Since  $u \circ (\operatorname{ad}(x)|_{\mathfrak{sl}_n}) = (\operatorname{ad}(x)|_{\mathfrak{sl}_n}) \circ u$  is to hold true for any  $x \in \mathfrak{sl}_n$ ,  $u = c \operatorname{Id}_{\mathfrak{sl}_n}$  for some  $c \in \dot{\mathbb{F}}$ . Whence,

$$S = \begin{pmatrix} a & 0 \\ 0 & t \end{pmatrix} \begin{pmatrix} b & 0 \\ 0 & c \operatorname{Id}_{\mathfrak{sl}_n} \end{pmatrix}$$

and we obtain the desired correspondence via  $(T, S) \leftrightarrow (a, b, c, t)$ . The statement about the group structure follows easily.  $\square$ 

Now, the structure of the vector space  $\operatorname{Hom}_{\operatorname{ad}}(S^2(\mathfrak{g}_1),\mathfrak{g}_0)$  of ad-equivariant maps when  $\mathfrak{g}_0 = \mathfrak{g}_1 = \mathfrak{gl}_n$  can be done with the help of Schur's Lemma once we know the ad-invariant subspaces that appear in the decomposition of  $S^2(\mathfrak{g}_1)$ . Since  $\mathfrak{gl}_n = \langle I_n \rangle \oplus \mathfrak{sl}_n$ ,

$$S^2(\langle I_n \rangle \oplus \mathfrak{sl}_n) = (S^0(\langle I_n \rangle) \otimes S^2(\mathfrak{sl}_n)) \oplus (S^1(\langle I_n \rangle) \otimes S^1(\mathfrak{sl}_n)) \oplus (S^2(\langle I_n \rangle) \otimes S^2(\mathfrak{sl}_n)) \oplus (S^$$

It is well known, however, that (see [9], P. 300)

$$S^{2}(\mathfrak{sl}_{n}) = \begin{cases} \langle I_{n} \rangle \oplus V_{5} & \text{if } n = 2 \\ \langle I_{n} \rangle \oplus \mathfrak{sl}_{3} \oplus V_{27} & \text{if } n = 3 \\ \langle I_{n} \rangle \oplus \mathfrak{sl}_{n} \oplus V_{n_{1}} \oplus V_{n_{2}} & \text{if } n \geq 4 \end{cases}$$

where  $V_j$  is an  $\mathfrak{sl}_n$ -irreducible subspace of dimension j,  $n_1 = \frac{n+3}{n-1} \binom{n}{2} \binom{n}{2}$ , and  $n_2 = \frac{n-3}{n-1} \binom{n}{2} \binom{n+1}{2}$ . In other words, we may rewrite it symbolically as,

$$S^{2}(\mathfrak{sl}_{n}) = \langle I_{n} \rangle \oplus (1 - \delta_{2n})\mathfrak{sl}_{n} \oplus W$$

where  $\delta_{2n}$  is the Kronecker symbol, and W does not contain any ad-invariant subspace isomorphic neither to  $\langle I_n \rangle$ , nor to  $\mathfrak{sl}_n$ . Therefore, using Schur's Lemma we conclude that,

$$\operatorname{Hom}_{\operatorname{ad}}(S^{2}(\langle I_{n}\rangle \oplus \mathfrak{sl}_{n}), \langle I_{n}\rangle \oplus \mathfrak{sl}_{n}) =$$

$$= \operatorname{Hom}_{\operatorname{ad}}(\langle I_{n}\rangle \oplus (1 - \delta_{2n})\mathfrak{sl}_{n} \oplus W \oplus \mathfrak{sl}_{n} \oplus \langle I_{n}\rangle, \langle I_{n}\rangle \oplus \mathfrak{sl}_{n})$$

$$= \operatorname{Hom}_{\operatorname{ad}}(\langle I_{n}\rangle, \langle I_{n}\rangle) \oplus \operatorname{Hom}_{\operatorname{ad}}(\langle I_{n}\rangle, \langle I_{n}\rangle)$$

$$\oplus (1 - \delta_{2n}) \operatorname{Hom}_{\operatorname{ad}}(\mathfrak{sl}_{n}, \mathfrak{sl}_{n}) \oplus \operatorname{Hom}_{\operatorname{ad}}(\mathfrak{sl}_{n}, \mathfrak{sl}_{n})$$

$$= \lambda \operatorname{Id}_{\langle I_{n}\rangle} \oplus \mu \operatorname{Id}_{\mathfrak{sl}_{n}} \oplus \nu \operatorname{Id}_{\langle I_{n}\rangle} \oplus (1 - \delta_{2n}) \epsilon \operatorname{Id}_{\mathfrak{sl}_{n}}, \quad \lambda, \mu, \nu, \epsilon \in \emptyset$$

which, after relabeling the generators, can be rewritten as

$$\operatorname{Hom}_{\operatorname{ad}}(S^{2}(\langle I_{n}\rangle \oplus \mathfrak{sl}_{n}), \langle I_{n}\rangle \oplus \mathfrak{sl}_{n}) = \lambda \operatorname{\mathbf{e}}_{\lambda} \oplus \mu \operatorname{\mathbf{e}}_{\mu} \oplus \nu \operatorname{\mathbf{e}}_{\nu} \oplus (1 - \delta_{2n}) \epsilon \operatorname{\mathbf{e}}_{\epsilon}$$

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